

IGS Workshop 2010

Real-time PPP with RTKLIB and IGS real-time satellite orbit and clock



Tokyo University of Marine Science and Technology

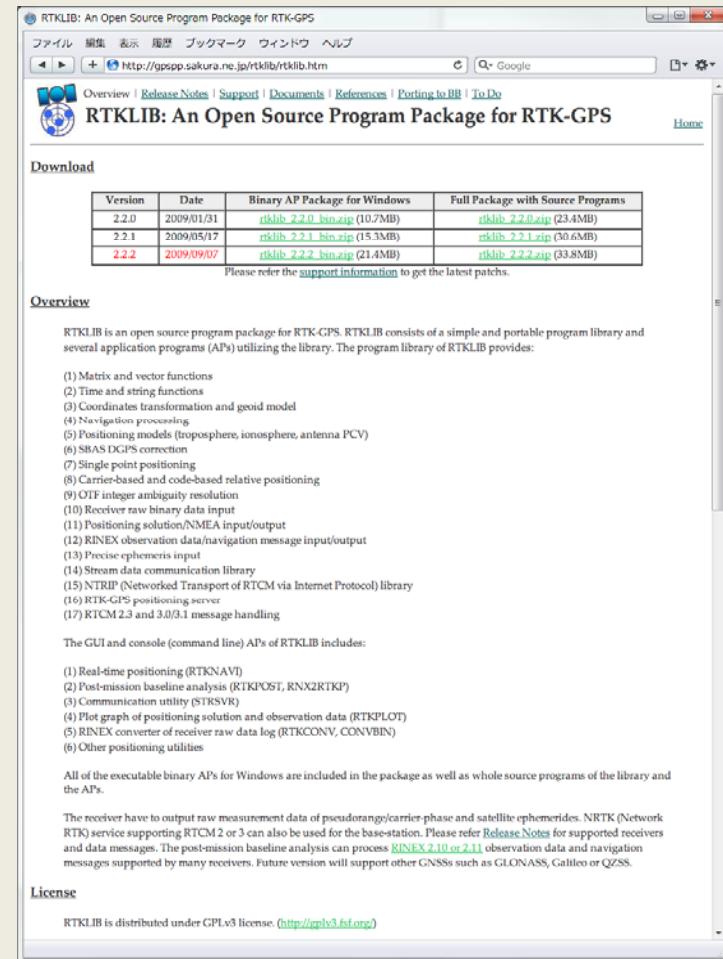
Tomoji TAKASU

Outline

- Introduction of RTKLIB
- RTKLIB 2.4.0
- PPP implementation in RTKLIB 2.4.0
- Test results of real-time PPP with IGS RT orbits/clocks

Introduction of RTKLIB

- Open source program package for RTK-GPS/GNSS
 - Whole source codes are freely available
 - License: GPLv3
 - 5000+ downloads (2.3.0)
- Portable library + several APs
 - ANSI C + socket/pthread ...
 - Portable command-line APs
 - GUI APs for Windows

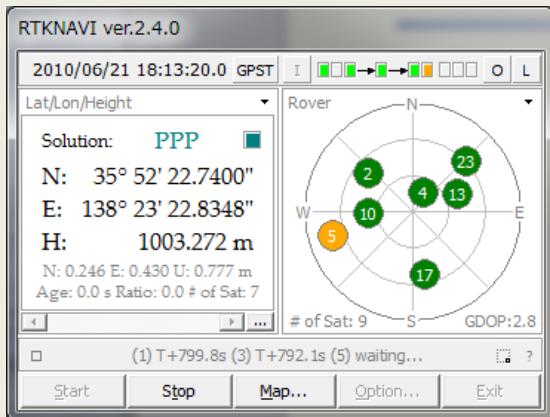


<http://gpspp.sakura.ne.jp/rtklib/rtklib.htm>

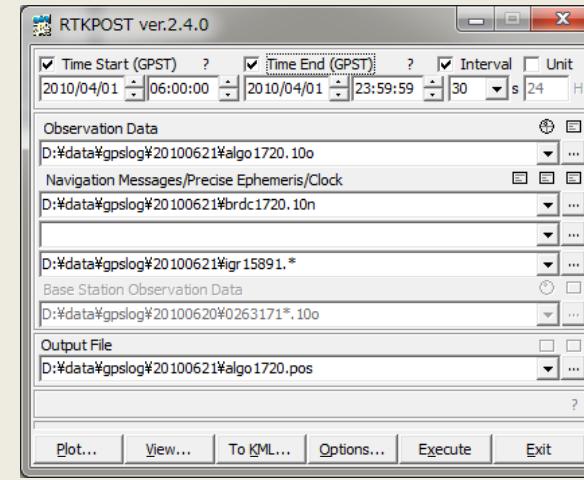
Features

- Standard and precise positioning algorithms with:
 - GPS, GLONASS, SBAS (and Galileo, QZSS)
- Various positioning modes:
 - Single, SBAS, DGPS, RTK, Static, Moving-base and PPP
- Supports many formats/protocols and receivers:
 - RINEX 2.1, RTCM v2/v3, NTRIP 1.0, NMEA183, SP3, RINEX CLK, ANTEX ...
 - NovAtel, Hemisphere, u-blox, SkyTraq ...
- External communication via:
 - Serial, TCP/IP, NTRIP and file streams

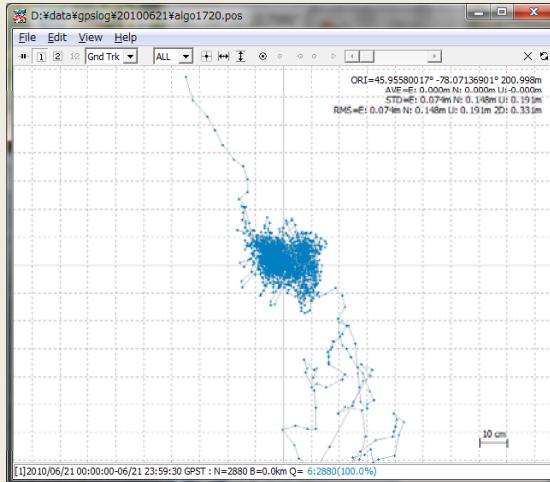
RTKLIB APs on Windows



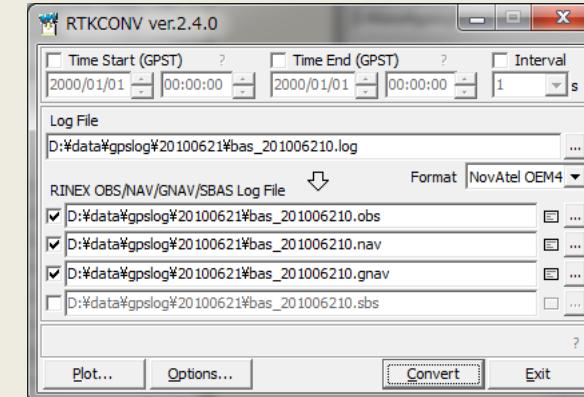
RTKNAVI: Real-time AP



RTKPOST: Post-Processing

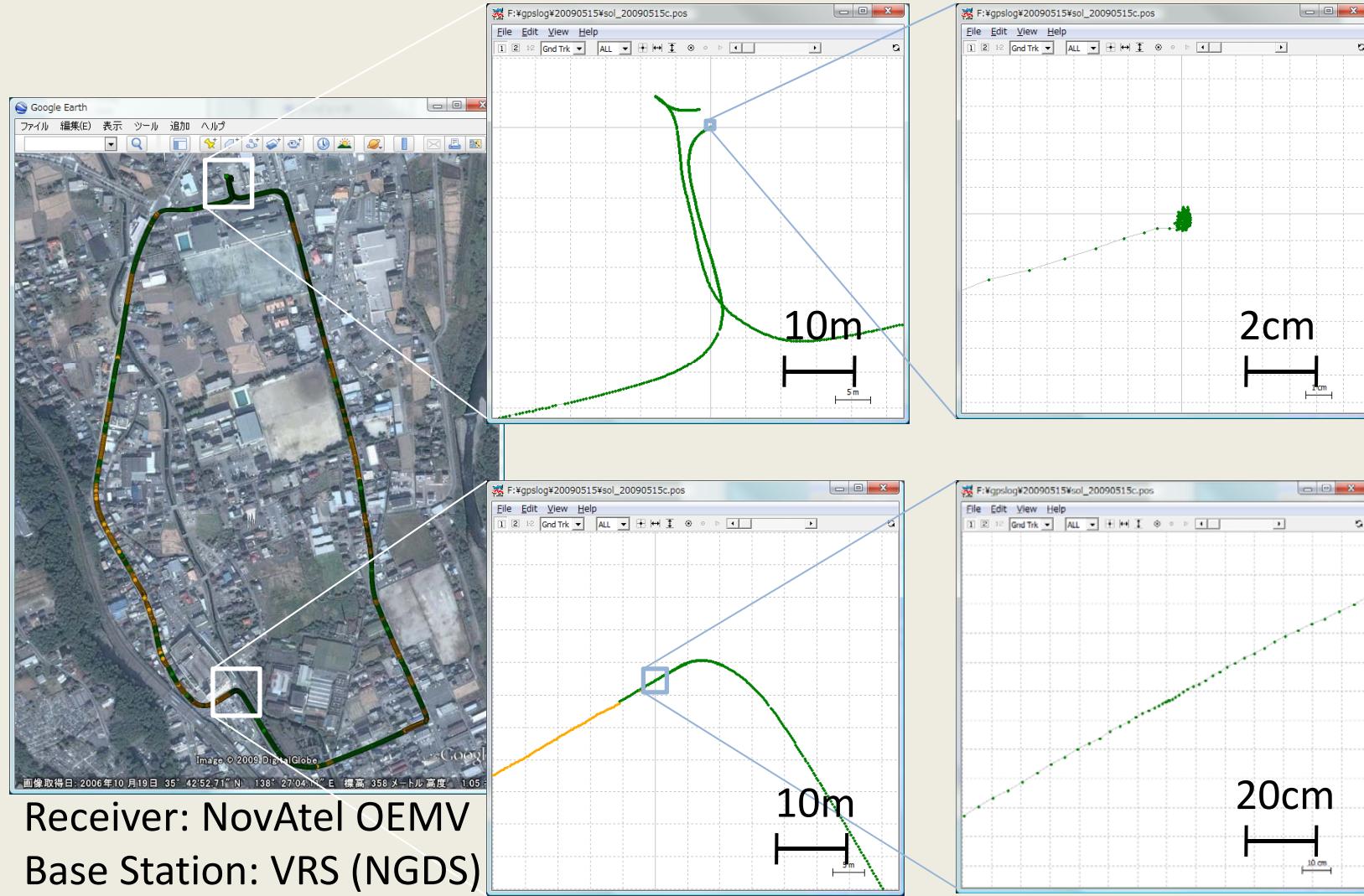


RTKPLOT: Plotting solutions



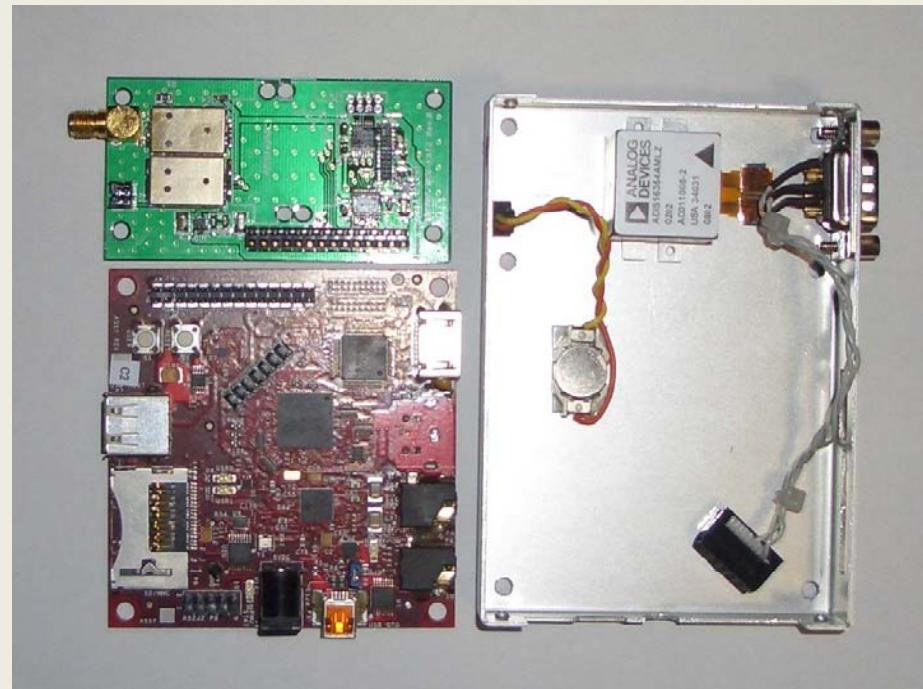
RTKCONV: RINEX converter

RTK Example by RTKNAVI



Low-Cost RTK Receiver with RTKLIB

- Implementation
 - CPU: Beagle Board
 - u-blox LEA-4T
 - Ubuntu 9.04
 - Wi-Fi, Bluetooth or HSDPA
- RTKRCV in RTKLIB
- GPS single-freq
- \$400 w/o option



RTKLIB 2.4.0

- Almost finished but still in work for tests
- Release in July or August
- New Features:
 - Real-time and Post-processing PPP
 - Supports long-baseline RTK up to 1,000 km
 - Supports additional formats and models: RINEX clock ext., ANTEX, earth tides, satellite antenna PCV, phase windup ...
 - Real-time plot by RTKPLOT

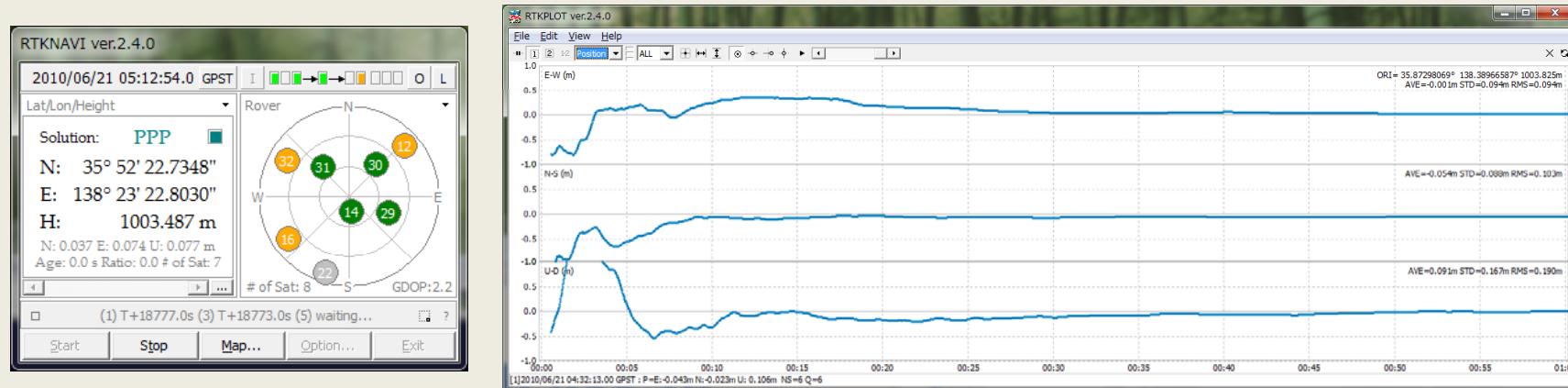
PPP Features in RTKLIB 2.4.0

- Kalman-Filter based parameter estimator
 - PPP-Kinematic or PPP-Static mode
- Atmosphere corrections:
 - Only L3-LC with dual-freq for Ionosphere
 - ZTD estimation with NMF for troposphere
- Solid earth tides by IERS 2003 (subset)
- Satellite and receiver antenna phase center models
 - ANTEX (IGS05.ATX) or NGS
- Antenna rotation effect for phase

Satellite Orbits and Clocks for PPP

- Post Processing:
 - SP3 for orbits and clocks
 - RINEX Clock extension for clocks (CODE-5s OK)
- Real-time:
 - Broadcast + RTCM v3 SSR draft (MT 1057, 1058, 1060, 1062, 1063, 1064, 1066, 1068)
 - Broadcast + SBAS long-term/fast corrections
 - QZSS LEX MT 10, 11 (in v.2.4.x)

PPP-Static with IGS RT Orbit/Clock



Solution RMS Error	After Convergence for		
	15 min	30 min	60 min
E-W	26.5 cm	15.4 cm	10.6 cm
N-S	15.4 cm	8.9 cm	7.5 cm
U-D	35.2 cm	16.7 cm	12.1 cm

2010/06/21, every 1H x 1Hz, 24 cases, NovAtel OEMV-3G
www.igs-ip.net:2101/CLK11 by BKG RTNet, GPS only

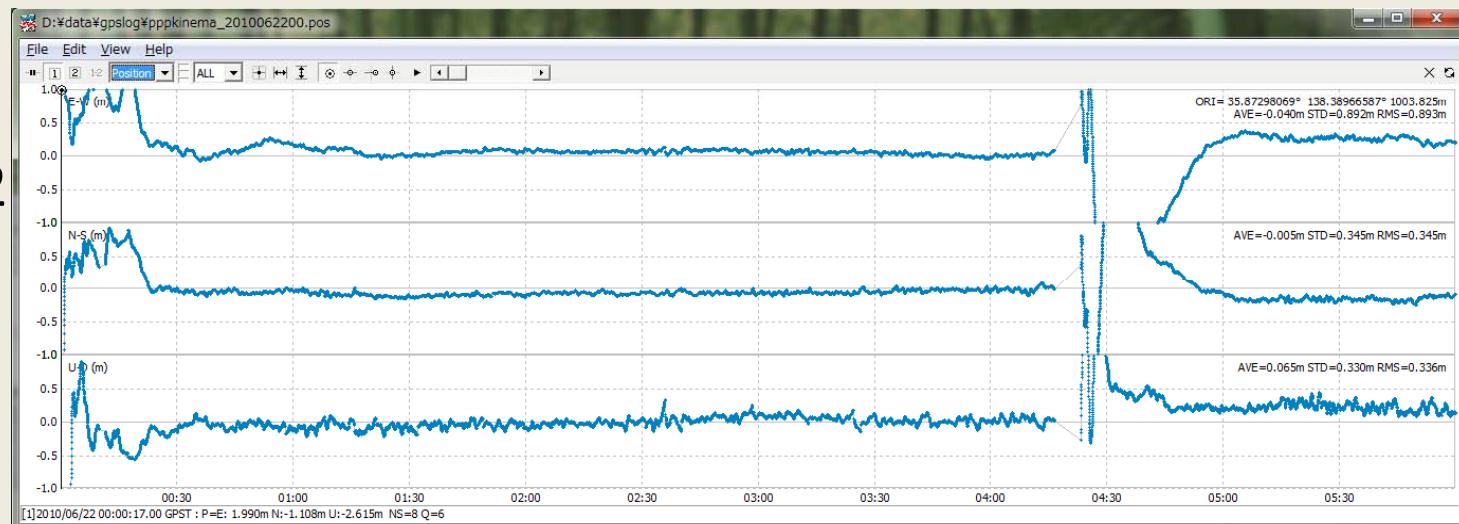
Example of Orbit/Clock Correction

RTCM SSR																															
SAT	Status	Intv(s)	IOD	URA	Da	T0	D0-A(m)	D0-C(m)	D0-R(m)	D1-A(mm)	D1-C(mm)	D1-R(mm)	C0(m)	C1(mm/s)	C2(mm/s)	C3(HR(m))	B4.1C/A	B4.1P(m)	B4.1CP	B4.1CD	B4.2C(m)	B4.2P(m)	B4.5I(m)	B4.6(m)	B10(m)	B11(m)	B12(m)	B13(m)	B14(m)	B15(m)	B16(m)
1	-	1	77	0	0	2010/06/21 03:34:55	0.492	1.364	-1.107	-0.003	0.112	-0.324	0.389	0.000	0.0000	0.000	1.50	0.97	0.00	0.00	1.61	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	
2	OK	1	3	0	0	2010/06/21 05:58:25	0.572	0.011	0.691	0.224	-0.060	-0.020	-0.345	0.000	0.0000	0.000	2.38	2.48	0.00	0.00	4.09	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
3	OK	1	62	0	0	2010/06/21 05:58:25	1.101	1.546	-0.369	0.108	-0.136	-0.232	-0.2172	0.000	0.0000	0.000	-1.65	-1.38	0.00	0.00	-2.27	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
4	OK	1	7	0	0	2010/06/21 05:58:25	1.217	-0.125	-0.057	-0.236	-0.048	-0.312	0.000	0.000	0.000	-0.53	-0.78	0.00	0.00	-1.30	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	
5	OK	1	59	0	0	2010/06/21 05:58:25	0.688	1.202	-0.711	0.017	-0.048	0.036	-0.271	0.000	0.0000	0.000	0.86	0.38	0.00	0.00	0.63	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
6	OK	1	66	0	0	2010/06/21 05:58:25	1.682	-0.254	0.485	-0.004	-0.288	0.032	-1.030	0.000	0.0000	0.000	-1.26	-1.20	0.00	0.00	-1.98	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
7	OK	1	84	0	0	2010/06/21 05:58:25	0.753	-0.995	1.308	-0.089	-0.048	0.020	0.338	0.000	0.0000	0.000	0.89	0.57	0.00	0.00	0.94	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
8	OK	1	58	0	0	2010/06/21 05:58:25	1.527	-0.181	0.162	-0.035	-0.268	0.168	0.666	0.000	0.0000	0.000	-1.82	-1.54	0.00	0.00	-2.54	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
9	OK	1	113	0	0	2010/06/21 05:58:25	1.610	-1.662	-1.085	-0.027	-0.368	0.048	-0.165	0.000	0.0000	0.000	-1.11	-1.01	0.00	0.00	-1.67	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
10	OK	1	16	0	0	2010/06/21 05:58:25	1.461	-0.697	0.324	0.037	-0.244	0.052	0.373	0.000	0.0000	0.000	-2.58	-1.91	0.00	0.00	-3.15	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
11	OK	1	98	0	0	2010/06/21 05:58:25	-0.486	-1.160	-0.304	0.058	-0.064	0.048	-0.026	0.000	0.0000	0.000	0.81	0.76	0.00	0.00	1.25	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
12	OK	1	48	0	0	2010/06/21 05:58:25	0.817	-1.664	-0.866	0.020	-0.028	-0.173	0.000	0.000	0.0000	0.000	1.24	0.91	0.00	0.00	1.51	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
13	OK	1	7	0	0	2010/06/21 05:58:25	-0.261	-0.224	0.836	-0.051	-0.148	0.044	0.853	0.000	0.0000	0.000	1.00	0.65	0.00	0.00	1.08	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
14	OK	1	79	0	0	2010/06/21 05:58:25	-0.424	1.096	1.156	-0.018	-0.108	-0.060	0.589	0.000	0.0000	0.000	-0.13	-0.03	0.00	0.00	-0.06	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
15	OK	1	97	0	0	2010/06/21 05:58:25	0.860	0.201	-0.444	-0.016	-0.155	-0.032	-0.497	0.000	0.0000	0.000	0.77	0.34	0.00	0.00	0.56	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
16	OK	1	6	0	0	2010/06/21 05:58:25	-0.351	0.318	0.344	0.007	-0.124	0.080	1.065	0.000	0.0000	0.000	-0.03	0.29	0.00	0.00	0.47	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
17	OK	1	57	0	0	2010/06/21 05:58:25	0.884	-1.397	-0.870	-0.041	-0.060	-0.040	-1.138	0.000	0.0000	0.000	0.82	0.48	0.00	0.00	0.79	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
18	OK	1	95	0	0	2010/06/21 05:58:25	-0.440	0.729	-0.418	0.020	-0.168	-0.036	0.504	0.000	0.0000	0.000	0.34	0.54	0.00	0.00	0.89	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
19	OK	1	44	0	0	2010/06/21 05:58:25	0.631	-0.286	-0.343	0.047	-0.068	0.016	-0.010	0.000	0.0000	0.000	0.95	1.63	0.00	0.00	2.69	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
20	OK	1	83	0	0	2010/06/21 05:58:25	-0.514	-0.736	0.304	-0.052	-0.076	-0.048	1.006	0.000	0.0000	0.000	-0.87	-0.34	0.00	0.00	-0.56	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
21	OK	1	86	0	0	2010/06/21 05:58:25	-0.432	0.931	-0.785	0.163	-0.132	-0.028	0.699	0.000	0.0000	0.000	0.64	0.89	0.00	0.00	1.46	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
22	OK	1	38	0	0	2010/06/21 05:58:25	0.651	-0.935	-0.534	-0.059	-0.052	0.044	-0.421	0.000	0.0000	0.000	2.66	2.67	0.00	0.00	4.41	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
23	OK	1	10	0	0	2010/06/21 05:58:25	0.628	0.076	0.728	0.053	-0.052	0.028	-0.699	0.000	0.0000	0.000	3.51	3.37	0.00	0.00	5.55	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

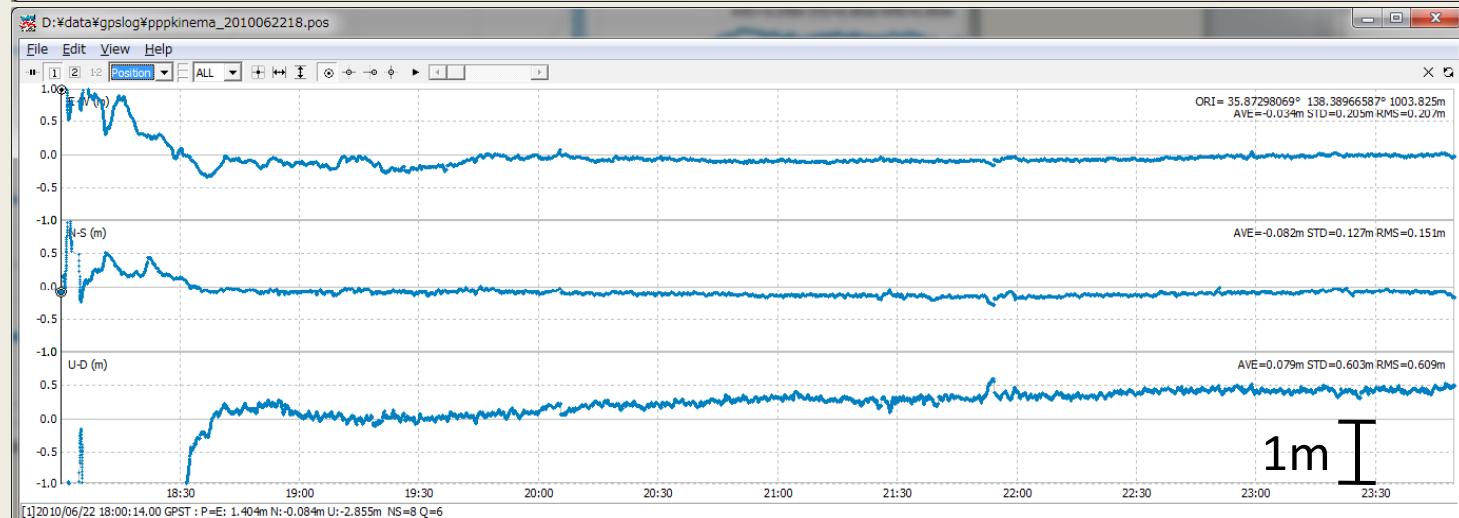
SAT	Status	Intv(s)	IOD	URA	Da	T0	D0-A(m)	D0-C(m)	D0-R(m)	D1-A(mm)	D1-C(mm)	D1-R(mm)	C0(m)	C1(mm/s)	C2(mm/s)	C3(HR(m))	B4.1C/A	B4.1P(m)	B4.1CP	B4.1CD	B4.2C(m)	B4.2P(m)	B4.5I(m)	B4.6(m)	B10(m)	B11(m)	B12(m)	B13(m)	B14(m)	B15(m)	B16(m)
1	-	1	77	0	0	2010/06/21 03:34:55	0.492	1.364	-1.107	-0.003	0.112	-0.324	0.389	0.000	0.0000	0.000	1.50	0.97	0.00	0.00	1.61	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
2	OK	1	3	0	0	2010/06/21 05:58:25	0.572	0.011	0.691	0.224	-0.060	-0.020	-0.345	0.000	0.0000	0.000	2.38	2.48	0.00	0.00	4.09	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
3	OK	1	62	0	0	2010/06/21 05:58:25	1.101	1.546	-0.369	0.108	-0.136	-0.232	-0.2172	0.000	0.0000	0.000	-1.65	-1.38	0.00	0.00	-2.27	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
4	OK	1	7	0	0	2010/06/21 05:58:25	1.217	-0.125	-0.057	-0.236	-0.048	-0.312	0.000	0.000	0.000	-0.53	-0.78	0.00	0.00	-1.30	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	
5	OK	1	59	0	0	2010/06/21 05:58:25	0.688	1.202	-0.711	0.017	-0.048	0.036	-0.271	0.000	0.0000	0.000	0.86	0.38	0.00	0.00	0.63	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
6	OK	1	66	0	0	2010/06/21 05:58:25	1.682	-0.254	0.485	-0.004	-0.288	0.032	-1.030	0.000	0.0000	0.000	-1.26	-1.20	0.00	0.00	-1.98	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
7	OK	1	84	0	0	2010/06/21 05:58:25	0.753	-0.995	1.308	-0.089	-0.048	0.020	0.338	0.000	0.0000	0.000	0.89	0.57	0.00	0.00	0.94	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
8	OK	1	58	0	0	2010/06/21 05:58:25	1.527	-0.181	0.162	-0.035	-0.268	0.168	0.666	0.000	0.0000	0.000	-1.82	-1.54	0.00	0.00	-2.54	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
9	OK	1	113	0	0	2010/06/21 05:58:25	1.610	-1.662	-1.085	-0.027	-0.368	0.048	-0.165	0.000	0.0000																

PPP-Kinematic with IGS RT-O/C

2010/6/22
0:00:00-
5:59:59



2010/6/22
18:00:00-
23:59:59



Current Concerns about IGS-IP

- Minor bug (?) in implementation of RTCM SSR formats
- Needs clear definitions for coordinates of orbit corrections and polarity of delta-clocks to avoid user confusion
- Lack of user algorithms for GLONASS broadcast ephemeris
- Not good quality of GLONASS orbits and clocks (outage or out-of-date corrections)

To Do List for Future Versions

- Supports RINEX 3.0
- Supports NTRIP 2.0
- Supports SOC format
- Supports other receivers' raw formats
- Supports download tool for online GNSS data
- Supports IONEX ionosphere corrections
- Supports INS/GNSS integration
- Supports RAIM
-

Summary

- Introduction of RTKLIB
- PPP implementation in RTKLIB 2.4.0
- Preliminary test results of real-time PPP with IGS RT orbits/clocks

<http://gpspp.sakura.ne.jp/rtklib/rtklib.htm>

or

Search “**RTKLIB**” by Google