

## Emlid Simple Report - Base

[details="Simple system report"]

...

app version: '26.2'

current\_network:

ip: 172.20.10.6

security: wpa-psk

ssid: "Juel\u2019s iPad"

enabled: true

mode: client

base\_mode:

base\_coordinates:

accumulation: 6

mode: fix-and-hold

output:

io\_type: lora

settings:

cloud:

mount\_point: ''

lora:

air\_rate: 9.1099999999999994

frequency: 902000

output\_power: 20

ntripsvr:

address: ''

mount\_point: ''

password: '\*\*\*\*'

port: -1

serial:

baud\_rate: 38400

device: ttyEXTS0

tcpcli:

address: localhost

port: 9001

tcpsvr:

port: 9000

rtcm3\_messages:

message\_1004:

enabled: false

frequency: 1

message\_1006:

enabled: true

frequency: 0.10000000000000001  
message\_1008:  
enabled: true  
frequency: 0.10000000000000001  
message\_1012:  
enabled: false  
frequency: 1  
message\_1033:  
enabled: false  
frequency: 0.10000000000000001  
message\_1074:  
enabled: true  
frequency: 1  
message\_1084:  
enabled: true  
frequency: 1  
message\_1094:  
enabled: true  
frequency: 1  
message\_1124:  
enabled: true  
frequency: 1  
message\_1230:  
enabled: false  
frequency: '1'  
bluetooth:  
enabled: false  
pairing:  
discoverable: false  
pin: '\*\*\*\*'  
camera\_trigger:  
duty\_cycle: 20  
enabled: false  
period: 2  
reverse\_polarity: false  
correction\_input:  
base\_corrections:  
io\_type: ntripcli  
settings:  
bluetooth:  
send\_position\_to\_base: false  
cloud:  
mount\_point: ''  
send\_position\_to\_base: true

lora:  
air\_rate: 9.1099999999999994  
frequency: 902000  
output\_power: 20  
send\_position\_to\_base: false

ntripcli:  
address: 132.239.152.175  
mount\_point: P224\_RTCM3  
password: '\*\*\*'  
port: 2103  
send\_position\_to\_base: false  
username: CRTNHERBRANS

serial:  
baud\_rate: 38400  
device: ttyEXTS0  
send\_position\_to\_base: false

tcpcli:  
address: localhost  
port: 10001  
send\_position\_to\_base: true

tcpsvr:  
port: 10000  
send\_position\_to\_base: true

device:  
privacy\_policy\_accepted: true  
role: null  
usage\_analysis\_accepted: true

logging:

logs:  
base:  
autostart: false  
format: RTCM3  
started: true

correction:  
autostart: false  
format: RTCM3  
started: true

raw:  
autostart: false  
format: UBX  
rinex\_options:  
logging\_interval: 1  
marker\_name: null  
pole\_height: null

satellite\_systems:  
 beidou: false  
 galileo: false  
 glonass: false  
 gps: true  
 qzss: false  
 sbas: false  
started: true  
solution:  
 autostart: false  
 format: LLH  
 started: true  
settings:  
 debug: false  
 interval: 24  
 overwrite: true  
position\_output:  
output1:  
 io\_type: 'off'  
 nmea\_settings:  
 bluetooth:  
 gga:  
 enabled: true  
 update\_rate: 1  
 gsa:  
 enabled: true  
 update\_rate: 1  
 gst:  
 enabled: true  
 update\_rate: 1  
 gsv:  
 enabled: true  
 update\_rate: 1  
 main\_talker\_id: gn  
 rmc:  
 enabled: true  
 update\_rate: 1  
 vtg:  
 enabled: true  
 update\_rate: 1  
 zda:  
 enabled: true  
 update\_rate: 1  
serial:

gga:  
 enabled: true  
 update\_rate: 1  
gsa:  
 enabled: true  
 update\_rate: 1  
gst:  
 enabled: true  
 update\_rate: 1  
gsv:  
 enabled: true  
 update\_rate: 1  
main\_talker\_id: gn  
rnc:  
 enabled: true  
 update\_rate: 1  
vtg:  
 enabled: true  
 update\_rate: 1  
zda:  
 enabled: true  
 update\_rate: 1  
tcpcli:  
gga:  
 enabled: true  
 update\_rate: 1  
gsa:  
 enabled: true  
 update\_rate: 1  
gst:  
 enabled: true  
 update\_rate: 1  
gsv:  
 enabled: true  
 update\_rate: 1  
main\_talker\_id: gn  
rnc:  
 enabled: true  
 update\_rate: 1  
vtg:  
 enabled: true  
 update\_rate: 1  
zda:  
 enabled: true

```
    update_rate: 1
tcpsvr:
  gga:
    enabled: true
    update_rate: 1
  gsa:
    enabled: true
    update_rate: 1
  gst:
    enabled: true
    update_rate: 1
  gsv:
    enabled: true
    update_rate: 1
  main_talker_id: gn
  rmc:
    enabled: true
    update_rate: 1
  vtg:
    enabled: true
    update_rate: 1
  zda:
    enabled: true
    update_rate: 1
settings:
  bluetooth:
    format: NMEA
  serial:
    baud_rate: 38400
    device: ttyEXTS0
    format: ERB
  tcpcli:
    address: localhost
    format: ERB
    port: 9000
  tcpsvr:
    format: LLH
    port: 9001
output2:
  io_type: 'off'
  nmea_settings:
    bluetooth:
      gga:
        enabled: true
```

update\_rate: 1  
gsa:  
  enabled: true  
  update\_rate: 1  
gst:  
  enabled: true  
  update\_rate: 1  
gsv:  
  enabled: true  
  update\_rate: 1  
main\_talker\_id: gn  
rmc:  
  enabled: true  
  update\_rate: 1  
vtg:  
  enabled: true  
  update\_rate: 1  
zda:  
  enabled: true  
  update\_rate: 1  
serial:  
  gga:  
    enabled: true  
    update\_rate: 1  
  gsa:  
    enabled: true  
    update\_rate: 1  
  gst:  
    enabled: true  
    update\_rate: 1  
  gsv:  
    enabled: true  
    update\_rate: 1  
  main\_talker\_id: gn  
  rmc:  
    enabled: true  
    update\_rate: 1  
  vtg:  
    enabled: true  
    update\_rate: 1  
  zda:  
    enabled: true  
    update\_rate: 1  
tcpcli:

gga:  
 enabled: true  
 update\_rate: 1  
gsa:  
 enabled: true  
 update\_rate: 1  
gst:  
 enabled: true  
 update\_rate: 1  
gsv:  
 enabled: true  
 update\_rate: 1  
main\_talker\_id: gn  
rmc:  
 enabled: true  
 update\_rate: 1  
vtg:  
 enabled: true  
 update\_rate: 1  
zda:  
 enabled: true  
 update\_rate: 1  
tcpsvr:  
gga:  
 enabled: true  
 update\_rate: 1  
gsa:  
 enabled: true  
 update\_rate: 1  
gst:  
 enabled: true  
 update\_rate: 1  
gsv:  
 enabled: true  
 update\_rate: 1  
main\_talker\_id: gn  
rmc:  
 enabled: true  
 update\_rate: 1  
vtg:  
 enabled: true  
 update\_rate: 1  
zda:  
 enabled: true



```
    update_rate: 1
settings:
  bluetooth:
    format: NMEA
  serial:
    baud_rate: 38400
    device: ttyEXTS0
    format: ERB
  tcpcli:
    address: localhost
    format: ERB
    port: 9000
  tcpsvr:
    format: LLH
    port: 9001
positioning_settings:
  elevation_mask_angle: 15
  glonass_ar_mode: false
  gnss_settings:
    positioning_systems:
      beidou: true
      galileo: true
      glonass: true
      gps: true
      qzss: true
    update_rate: 5
  gps_ar_mode: fix-and-hold
  max_horizontal_acceleration: '1'
  max_vertical_acceleration: '1'
  positioning_mode: static
  snr_mask: 35
'''
```

[/details]