

[details="Simple system report"]

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app version: 2.23.4-dev-r0

'wifi_status, interface: wlan0':

- wifi_mode: infrastructure

- ip: 192.168.8.101

is_added: true

is_connected: true

is_visible: false

mac_address: FC:DB:B3:7D:9E:A1

security: wpa-psk

ssid: WiFi-pole

uuid: abb55586-25f9-4de7-8d92-6514940e69ba

base mode:

base coordinates:

accumulation: 2

antenna offset:

east: '0'

north: '0'

up: 0.080000000000000002

coordinates:

- 3656147.0159999998

- 1394518.629

- 5020012.9720000001

format: xyz

mode: manual

output:

enabled: false

io_type: tcpsvr

port: 9000

rtcm3 messages:

'1002':

enabled: true

frequency: 1.0

'1006':

enabled: true

frequency: 0.100000000000000001

'1010':

enabled: true

frequency: 1.0

'1097':

enabled: false

frequency: 1.0

'1107':

enabled: false

frequency: 1.0

'1117':

enabled: false

frequency: 1.0

'1127':

enabled: false
frequency: 1.0
bluetooth:
discoverable: true
enabled: true
pin: '****'
camera:
duty cycle: 20
enable: false
period: 2
polarity: false
constraints:
lora:
frequency:
- - 863000
- 928000
correction input:
input2:
address: euref-ip.net
enabled: true
format: RTCM3
io_type: ntripcli
mount_point: JOZ200POL0
password: '****'
port: 2101
send_position_to_base: true
username: *****
device: null
logging:
base:
format: RTCM3
started: true
correction:
format: RTCM3
started: true
debug: false
interval: 24
overwrite: true
raw:
format: UBX
started: true
solution:
format: LLH
started: true
position output:
output1:
enabled: true
format: NMEA
io_type: bluetooth
output2:

```
enabled: false
format: LLH
io_type: tcpsvr
port: 9001
rtk settings:
  elevation mask angle: 15
  glonass ar mode: 'on'
  gps ar mode: fix-and-hold
  max horizontal acceleration: 1.0
  max vertical acceleration: 1.0
  positioning mode: kinematic
  positioning systems:
    compass: false
    galileo: true
    glonass: true
    gps: true
    qzss: false
    sbas: false
  snr mask: 35
  update rate: 5
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