

Status	Config	Logs	
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Base **Rover**

Stop **Save** **:**

reach_kinematic_default.conf

Positioning mode

kinematic

Used positioning systems

gps, sbas, glo, gal, qzs, comp **6**

Dynamics model of the rover(Kinematic and dgps only)

off

u-blox configuration file

GPS_GLONASS_5Hz

Input source for base corrections

serial

USB

115200

Input format for base corrections

rtcm3

Solution 1 output path

file

Solution 1 output format

llh

Solution 2 output path

tcpsvr

9000

Solution 2 output format

nmea

Raw data log for onboard receiver

file

Raw data log for base corrections

file

Base antenna coordinates

rtcm

Advanced settings