

Status	Config	Logs	
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Base **Rover**

Stop **Save & Load**

Output path for corrections

serial

USB

115200

Output format

rtcm3

RTCM3 messages for output

1002, 1006, 1008, 1010, 1019, 1020 6

Base latitude

33.726962164

Base longitude

-83.299158376

Base height

118.2579

GPS_GLONASS_5Hz.cmd